

Solving 2D-BKDV Equation by a Sub-ODE Method

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Abstract. In this paper, we derive exact traveling wave solutions of 1D-BKDV equation and 2D-BKDV equation by a proposed Bernoulli sub-ODE method. The method appears to be efficient in seeking exact solutions of nonlinear equations.

Keywords: Bernoulli sub-ODE method, traveling wave solutions, exact solution, evolution equation, BKDV equation

1. Introduction

During the past four decades or so searching for explicit solutions of nonlinear evolution equations by using various different methods have been the main goal for many researchers, and many powerful methods for constructing exact solutions of nonlinear evolution equations have been established and developed such as the inverse scattering transform, the Darboux transform, the tanh-function expansion and its various extension, the Jacobi elliptic function expansion, the homogeneous balance method, the sine-cosine method, the rank analysis method, the exp-function expansion method and so on [1-13]. In this paper, we proposed a Bernoulli sub-ODE method to construct exact traveling wave solutions for NLEES.

The rest of the paper is organized as follows. In Section 2, we describe the Bernoulli sub-ODE method for finding traveling wave solutions of nonlinear evolution equations, and give the main steps of the method. In the subsequent sections, we will apply the method to find exact traveling wave solutions of the 1D-BKDV equation and the 2D-BKDV equation. In the last Section, some conclusions are presented.

2. Description of the Bernoulli Sub-ODE method

In this section we present the solutions of the following ODE:

$$G' + \lambda G = \mu G^2, \quad (2.1)$$

where $\lambda \neq 0, G = G(\xi)$

When $\mu \neq 0$, Eq. (2.1) is the type of Bernoulli equation, and we can obtain the solution as

$$G = \frac{1}{\frac{\mu}{\lambda} + d e^{\lambda \xi}}, \quad (2.2)$$

where d is an arbitrary constant.

Suppose that a nonlinear equation, say in two or three independent variables x, y and t , is given by

$$P(u, u_t, u_x, u_y, u_u, u_{xt}, u_{yt}, u_{xx}, u_{yy}, \dots) = 0 \quad (2.3)$$

where $u = u(x, y, t)$ is an unknown function, P is a polynomial in $u = u(x, y, t)$ and its various partial derivatives,

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in which the highest order derivatives and nonlinear terms are involved. By using the solutions of Eq. (2.1), we can construct a series of exact solutions of nonlinear equations:

Step 1. We suppose that

$$u(x, y, t) = u(\xi), \xi = \xi(x, y, t) \quad (2.4)$$

the traveling wave variable (2.4) permits us reducing Eq. (2.3) to an ODE for $u = u(\xi)$

$$P(u, u', u'', \dots) = 0 \quad (2.5)$$

Step 2. Suppose that the solution of (2.5) can be expressed by a polynomial in G as follows:

$$u(\xi) = \alpha_m G^m + \alpha_{m-1} G^{m-1} + \dots \quad (2.6)$$

where $G = G(\xi)$ satisfies Eq. (2.1), and $\alpha_m, \alpha_{m-1}, \dots$ are constants to be determined later, $\alpha_m \neq 0$. The positive integer m can be determined by considering the homogeneous balance between the highest order derivatives and nonlinear terms appearing in (2.5).

Step 3. Substituting (2.6) into (2.5) and using (2.1), collecting all terms with the same order of G together, the left-hand side of Eq. (2.5) is converted into another polynomial in G . Equating each coefficient of this polynomial to zero, yields a set of algebraic equations for $\alpha_m, \alpha_{m-1}, \dots, \lambda, \mu$.

Step 4. Solving the algebraic equations system in Step 3, and by using the solutions of Eq. (2.1), we can construct the traveling wave solutions of the nonlinear evolution equation (2.5).

In the subsequent sections we will illustrate the proposed method in detail by applying it to 1D-BKDV equation and 2D-BKDV equation.

3. Application Of the Bernoulli Sub-ODE Method For 1D-BKDV Equation

In this section, we will consider the following 1D-BKDV equation:

$$u_t + \alpha u u_x + \beta u_{xx} + \gamma u_{xxx} = 0 \quad (3.1)$$

Suppose that

$$u(x, t) = u(\xi), \xi = k(x - ct) \quad (3.2)$$

where c, k are constants that to be determined later.

By (3.2), (3.1) is converted into an ODE

$$-cu' + \alpha u u' + \beta k u'' + \gamma k^2 u''' = 0 \quad (3.3)$$

Integrating the ODE (3.3) once, we obtain

$$-cu + \frac{\alpha}{2} u^2 + \beta k u' + \gamma k^2 u'' = g \quad (3.4)$$

where g is the integration constant that can be determined later.

Suppose that the solution of (3.4) can be expressed by a polynomial in G as follows:

$$u(\xi) = \sum_{i=0}^m a_i G^i \quad (3.5)$$

where a_i are constants, and $G = G(\xi)$ satisfies Eq.(2.1). Balancing the order of u^2 and u'' in Eq.(3.4), we have $2m = m + 2 \Rightarrow m = 2$. So Eq.(3.5) can be rewritten as

$$u(\xi) = a_2 G^2 + a_1 G + a_0, a_2 \neq 0 \quad (3.6)$$

where a_2, a_1, a_0 are constants to be determined later.

Substituting (3.6) into (3.4) and collecting all the terms with the same power of G together, equating each coefficient to zero, yields a set of simultaneous algebraic equations as follows:

$$G^0 : -ca_0 - g + \frac{1}{2}\alpha a_0^2 = 0$$

$$G^1 : -ca_1 + \alpha a_1 a_0 + \beta k a_1 \mu + \gamma k^2 a_1 \mu^2 = 0$$

$$G^2 : -ca_2 + 2\beta k a_2 \mu + \alpha a_0 a_2 - \beta k a_1 \lambda + \frac{1}{2}\alpha a_1^2 + 4\gamma k^2 a_2 \mu^2 - 3\gamma k^2 a_1 \mu \lambda = 0$$

$$G^3 : -2\beta k a_2 \lambda - 10\gamma k^2 a_2 \mu \lambda + \alpha a_1 a_2 + 2\gamma k^2 a_1 \lambda^2 = 0$$

$$G^4 : \frac{1}{2}\alpha a_2^2 + 6\gamma k^2 a_2 \lambda^2 = 0$$

Solving the algebraic equations above, yields:

Case 1:

$$a_2 = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}, a_1 = 0, a_0 = a_0, k = -\frac{1}{5}\frac{\beta}{\gamma\mu}, c = \frac{1}{25}\frac{-6\beta^2 + 25\alpha a_0\gamma}{\gamma}, g = -\frac{1}{50}\frac{a_0(-12\beta^2 + 25\alpha a_0\gamma)}{\gamma} \quad (3.7)$$

where a_0 is an arbitrary constants.

Substituting (3.7) into (3.6), we get that

$$u_1(\xi) = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}G^2 + a_0, \quad \xi = -\frac{1}{5}\frac{\beta}{\gamma\mu}\left(x - \frac{1}{25}\frac{-6\beta^2 + 25\alpha a_0\gamma}{\gamma}t\right) \quad (3.8)$$

where k, c are defined as in (3.7).

Combining with Eq. (2.2), we can obtain the traveling wave solutions of (3.1) as follows:

$$u_1(\xi) = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}\left(\frac{1}{\frac{\mu}{\lambda} + de^{\lambda\xi}}\right)^2 + a_0 \quad (3.9)$$

where a_0, d are arbitrary constants, and $\xi = -\frac{1}{5}\frac{\beta}{\gamma\mu}\left(x - \frac{1}{25}\frac{-6\beta^2 + 25\alpha a_0\gamma}{\gamma}t\right)$.

Case 2:

$$a_2 = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}, a_1 = \frac{24\beta^2\lambda}{25\alpha\gamma\mu}, a_0 = a_0, k = \frac{1}{5}\frac{\beta}{\gamma\mu}, c = \frac{1}{25}\frac{6\beta^2 + 25\alpha a_0\gamma}{\gamma}, g = -\frac{1}{50}\frac{a_0(12\beta^2 + 25\alpha a_0\gamma)}{\gamma} \quad (3.10)$$

where a_0 is an arbitrary constants.

Substituting (3.10) into (3.6), we get that

$$u_2(\xi) = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}G^2 + \frac{24\beta^2\lambda}{25\alpha\gamma\mu}G + a_0, \quad \xi = \frac{1}{5}\frac{\beta}{\gamma\mu}\left(x - \frac{1}{25}\frac{6\beta^2 + 25\alpha a_0\gamma}{\gamma}t\right) \quad (3.11)$$

where k, c are defined as in (3.7).

Combining with Eq. (2.2), we can obtain the traveling wave solutions of (3.1) as follows:

$$u_2(\xi) = -\frac{12\beta^2\lambda^2}{25\alpha\gamma\mu^2}\left(\frac{1}{\frac{\mu}{\lambda} + de^{\lambda\xi}}\right)^2 + \frac{24\beta^2\lambda}{25\alpha\gamma\mu}\left(\frac{1}{\frac{\mu}{\lambda} + de^{\lambda\xi}}\right) + a_0 \quad (3.12)$$

where a_0, d are arbitrary constants, and $\xi = \frac{1}{5}\frac{\beta}{\gamma\mu}\left(x - \frac{1}{25}\frac{6\beta^2 + 25\alpha a_0\gamma}{\gamma}t\right)$.

Remark : Our results (3.9) and (3.12) are new families of exact traveling wave solutions for Eq. (3.1).

4. Application Of the Bernoulli Sub-ODE Method For 2D-BKDV Equation

In this section, we will consider the following 2D-BKDV equation:

$$(u_t + \alpha uu_x + \beta u_{xx} + su_{xxx})_x + \gamma u_{yy} = 0 \quad (4.1)$$

Suppose that

$$u(x, y, t) = u(\xi), \xi = k(x + y - ct) \quad (4.2)$$

where c, k are constants that to be determined later.

By (4.2), (4.1) is converted into an ODE

$$(-cu' + \alpha uu' + \beta ku'' + sk^2u''')' + \gamma u'' = 0 \quad (4.3)$$

Integrating the ODE (4.3) once, we obtain

$$-cu' + \alpha uu' + \beta ku'' + sk^2u''' + \gamma u'' = g \quad (4.4)$$

where g is the integration constant that can be determined later.

Suppose that the solution of (4.4) can be expressed by a polynomial in G as follows:

$$u(\xi) = \sum_{i=0}^m a_i G^i \quad (4.5)$$

where a_i are constants, and $G = G(\xi)$ satisfies Eq. (2.1). Balancing the order of uu' and u''' in Eq.(4.4), we have $m + m + 1 = m + 3 \Rightarrow m = 2$. So Eq.(4.5) can be rewritten as

$$u(\xi) = a_2 G^2 + a_1 G + a_0, a_2 \neq 0 \quad (4.6)$$

where a_2, a_1, a_0 are constants to be determined later.

Substituting (4.6) into (4.4) and collecting all the terms with the same power of G together, equating each coefficient to zero, yields a set of simultaneous algebraic equations as follows:

$$G^0: -g = 0$$

$$G^1: -\alpha a_1 a_0 \lambda + \beta k a_1 \lambda^2 - s k^2 a_1 \lambda^3 - \gamma a_1 \lambda - c a_1 \lambda = 0$$

$$G^2: 2c a_2 \lambda - c a_1 \mu - \alpha a_1^2 \lambda - 3\beta k a_1 \mu \lambda - 2\alpha a_0 a_2 \lambda + \alpha a_0 a_1 \mu = 0$$

$$G^3: -3\alpha a_1 a_2 \mu - 2c a_2 \mu + 38s k^2 a_2 \mu \lambda^2 + 2\beta k a_1 \mu^2 + 2\alpha a_0 a_2 \mu + 2\gamma a_2 \mu - 12s k^2 \mu^2 a_1 \lambda - 10\beta k a_2 \mu \lambda + \alpha a_1^2 \mu = 0$$

$$G^4: -54s a_2 k^2 \mu^2 \lambda - 2\alpha a_2^2 \lambda + 6s k^2 \mu^3 a_1 + 3\alpha a_2 a_1 \mu + 6\beta k \mu^2 a_2 = 0$$

$$G^5: 24s a_2 k^2 \mu^3 + 2\alpha a_2^2 \mu = 0$$

Solving the algebraic equations above, yields:

Case 1:

$$a_2 = -\frac{12\beta^2 \mu^2}{25s\lambda^2 \alpha}, a_1 = \frac{24\beta^2 \mu}{25s\lambda \alpha}, a_0 = a_0,$$

$$c = \frac{1}{25} \frac{25\alpha a_0 s + 6\beta^2 + 25\gamma s}{s}, g = 0, k = -\frac{1}{5} \frac{\beta}{s\lambda} \quad (4.7)$$

where a_0 is an arbitrary constants.

Substituting (4.7) into (4.6), we get that

$$u_1(\xi) = -\frac{12\beta^2 \mu^2}{25s\lambda^2 \alpha} G^2 + \frac{24\beta^2 \mu}{25s\lambda \alpha} G + a_0, \xi = -\frac{1}{5} \frac{\beta}{s\lambda} (x + y - \frac{1}{25} \frac{25\alpha a_0 s + 6\beta^2 + 25\gamma s}{s} t) \quad (4.8)$$

where k, c are defined as in (4.7).

Combining with Eq. (2.2), we can obtain the traveling wave solutions of (4.1) as follows:

$$u_1(\xi) = -\frac{12\beta^2 \mu^2}{25s\lambda^2 \alpha} \left(\frac{1}{\frac{\mu}{\lambda} + de^{2\xi}} \right)^2 + \frac{24\beta^2 \mu}{25s\lambda \alpha} \left(\frac{1}{\frac{\mu}{\lambda} + de^{2\xi}} \right) + a_0 \quad (4.9)$$

where a_0, d are arbitrary constants, and $\xi = -\frac{1}{5} \frac{\beta}{s\lambda} (x + y - \frac{1}{25} \frac{25\alpha a_0 s + 6\beta^2 + 25\gamma s}{s} t)$.

Case 2:

$$a_2 = -\frac{12\beta^2 \mu^2}{25s\lambda^2 \alpha}, a_1 = 0, a_0 = a_0, c = \frac{1}{25} \frac{25\alpha a_0 s - 6\beta^2 + 25\gamma s}{s}, g = 0, k = \frac{1}{5} \frac{\beta}{s\lambda}, \quad (4.10)$$

where a_0 is an arbitrary constants.

Substituting (4.10) into (4.6), we get that

$$u_2(\xi) = -\frac{12\beta^2\mu^2}{25s\lambda^2\alpha}G^2 + \frac{24\beta^2\mu}{25s\lambda\alpha}G + a_0, \quad \xi = \frac{1}{5s\lambda}(x+y - \frac{1}{25}\frac{25\alpha a_0 s - 6\beta^2 + 25\gamma s}{s}t) \quad (4.11)$$

where k, c are defined as in (4.7).

Combining with Eq. (2.2), we can obtain the traveling wave solutions of (4.1) as follows:

$$u_2(\xi) = -\frac{12\beta^2\mu^2}{25s\lambda^2\alpha}\left(\frac{1}{\frac{\mu}{\lambda} + de^{\lambda\xi}}\right)^2 + \frac{24\beta^2\mu}{25s\lambda\alpha}\left(\frac{1}{\frac{\mu}{\lambda} + de^{\lambda\xi}}\right) + a_0 \quad (4.12)$$

where a_0, d are arbitrary constants, and $\xi = \frac{1}{5s\lambda}(x+y - \frac{1}{25}\frac{25\alpha a_0 s - 6\beta^2 + 25\gamma s}{s}t)$.

Remark : Our results (4.9) and (4.12) are new families of exact traveling wave solutions for Eq. (4.1).

5. Conclusions

We have seen that some new traveling wave solutions of 1D and 2D-BKDV equation are successfully found by using the Bernoulli sub-ODE method. The main points of the method are that assuming the solution of the ODE reduced by using the traveling wave variable as well as integrating can be expressed by an m -th degree polynomial in G , where $G = G(\xi)$ is the general solutions of a Bernoulli sub-ODE equation. The positive integer m can be determined by the general homogeneous balance method, and the coefficients of the polynomial can be obtained by solving a set of simultaneous algebraic equations. Also this method can be used to many other nonlinear problems.

6. References

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